



for QUATTRO-G3D

DeltaQ is a powerful GNSS receiver disigned for high accuracy applications with requirements of the three-dimentional position and attitude, linear and angular velocity determination of the four-antenna system using the dual frequency code and carrier data from four antennas.

216 channels of single or dual frequency GPS, Galileo and GLONASS in a small attractive, sturdy, and watertight box, which contains Quattro-G3D board.

DELTAQ

| Standard Configuration | | Total 216 channels: all-in-view (GPS 1/L2, Galileo F1 |
|---|------------------------------|--|
| GPS L1/L2/L2C (all anennas) GLONASS L1/L2 (main antenna only) | Description | GLONASS L1/L2, QZSS, Compass B1, SBAS L1) integrated receiver, rugged aluminum housing with TriPad interface |
| • Update rate 1 Hz | Tracking Specification | |
| • RAIM • TriPad interface | | GPS C/A, P1, P2, L2C (L+M) Galileo F1 (B+C) |
| RS232 serial port (460.8 kbps) A External GNSS Antenna TNC Female connectors | Signals Tracked** | GLINASS C/A, L2C, P1, P2 (main antenna only) QZSS C/A, L1C (I+Q), L2C (L+M), SAIF |
| Ontional Feature | | Compass B1 SBAS L1 |
| Galileo F1 | Performance Specifications | |
| • 07SS | r entermance specifications | Real time beading - 0.001/L [rad] BMS*** |
| Compass B1 Hadde acts 5112 10112 001121 | Attitude accuracy | Roll/Pitch - 0.0065/L [rad] RMS*** Angular velocity determination - 0.05/L [rad/s]*** |
| Update rate 5HZ, TUHZ, 2UHZ ^{**} | | Determination of antennas relative position - 10 mm RMS |
| Attitude/RTK rate T Hz, 5Hz, TUHz, 2UHz | Autonomous | < 2 m |
| Data recording up to 2048WB Multi-Base Code Differential Rover | Static, Fast Static Accuracy | Horizontal: 0.3 cm + 0.1 ppm * base_line_length**** |
| Code Differential Base Advanced Multipath Reduction | Kinematic Accuracy | Horizontal: 1 cm + 1 ppm * base_line_length Vertical: 1.5 cm + 1.5 ppm * base_line_length |
| Two event markers | BTK (OTF) Accuracy | Horizontal: 1 cm + 1 ppm * base_line_length |
| Two 1 PPS timing strobes | | Vertical: 1.5 cm + 1.5 ppm * base_line_length |
| 1 PPS level converter | DGPS Accuracy | < 0.25 m post processing; < 0.5 m real-ume |
| CAN port | Linear velocity accuracy | 0.1 m/s |
| External Reference Frequency Input/Output | Cold start; warm start | <35 seconds; <5 seconds |
| External Reference Output Frequency converter | Power Specification | |
| Up to 3 high-speed RS232 serial ports | Battery | External |
| High-speed RS232/RS422 serial port | External Input Voltage | +6 to +35 volts (1 external power port) |
| USB port | Power Consumption | 5.2 W |
| Ethernet | 1/0 | F |
| • WAAS/EGNOS/MSAS (SBAS) | GNSS Antenna Connector | Four 50 Ohm TNC, +5 VDC (100 mA) to power LNA |
| | Communication Ports | Three serial RS232 ports (up to 460.8 kbps) High-speed RS232/RS422 serial port (up to 460.8 Kbps) High-speed USB 2.0 device port (480 Mbps) Full-duplex 10BASE-T/100BASE-TX Ethernet port Bluetooth V1.2 Class 2 supporting SPP Slave Profile CAN 2.0 |
| | Other I/O Signals | Two 1 PPS synchronized PPS level converter (0 to 4V on 500hm load) Two Event Markers IRIG External Reference Frequency Input/Output External Reference Output Frequency Converter (5/10/20MHz, -2dBm to +13dBm, step 1dB) |
| | Status Indicator | Two LEDs, two function keys (TriPad) |
| | Memory & Recording | |
| | Internal Memory | Up to 2048MB of on-board non-removable memory for data storage |
| | Raw Data Recording | Up to 20 times per second (20Hz)* |
| 3 | Real Time Data | |
| 1. GNSS Receiver with on-board Memory | Input/Output | JPS, RTCM SC104 v. 2.x and 3.x, CMR |
| 2. GNSS Interconnect Board | Output | NMEA 0183 v. 2.x and 3.0, BINEX |
| 3. Communication and Power Ports | Environmental Specifications | · · · · · · · · · · · · · · · · · · · |
| 4. On/Off and Function Buttons and LEDs | | Aluminum extrusion, waterproof IP67 |
| 5. Reference Converter Board (optional) | Operating Temperature | -40° C to +75° C |
| 6. External GNSS Antenna Connector | Storage Temperature | -45° C to +85° C |
| | Humidity | 95% |
| ** The simultaneous signals tracking is limited by the number of the | Dimensions | 109 x 35 x 141/max 160 with connectors |
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** The simultaneous signals tracking is limited by the number of the available channels. By the attitude determination GPS L1/L2/L2C and GLONASS L1/L2 tracking should be active only

Weight

JAVAD GNSS

www.javad.com Rev.2.2 February 26, 2013

Specifications are subject to change without notice



*** Where L is the antenna separation in [m] **** For good observation conditions and proper length of observation session

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